

Generating sounds for actions and scenes

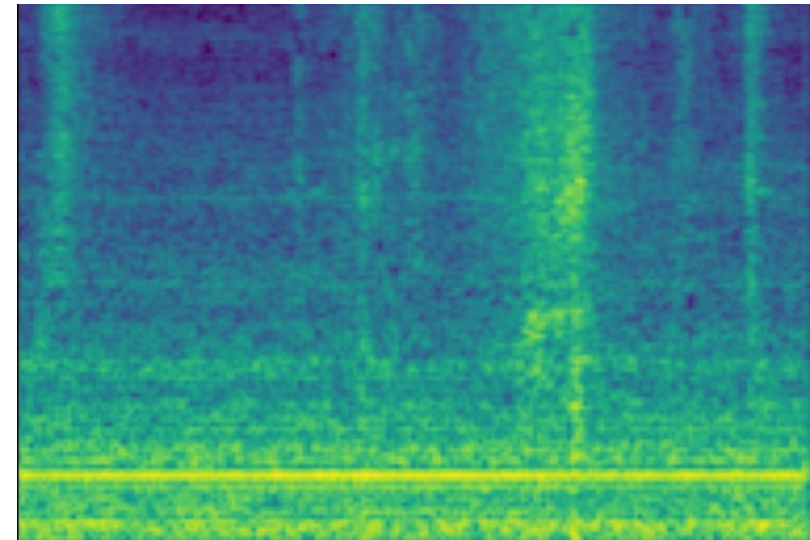
Kristen Grauman
University of Texas at Austin



Generating visually consistent sounds

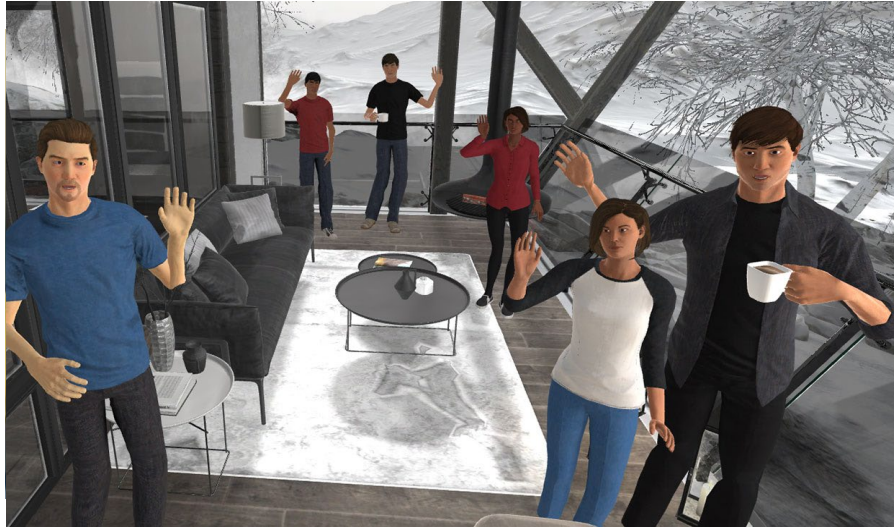


Silent video



Plausible audio

Immersive audio-visual (re-)generation



Augmented and virtual reality



Gaming

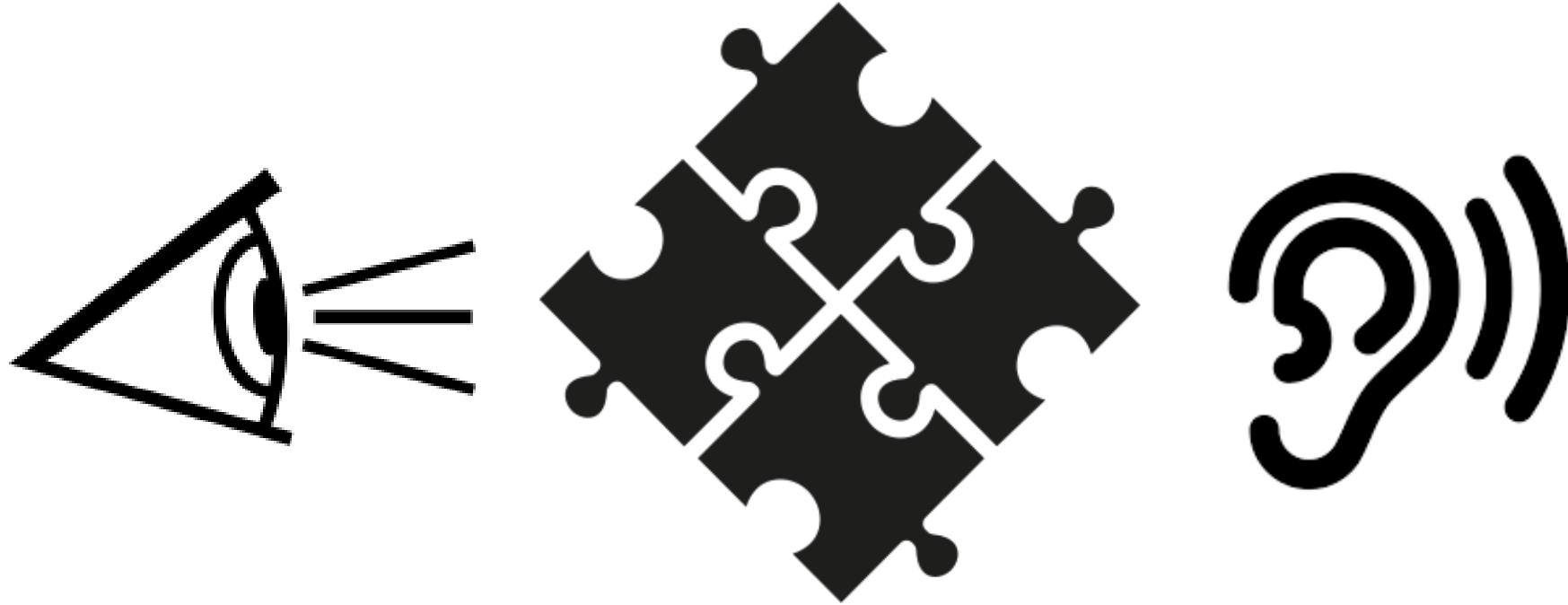


Film dubbing and Foley



Video conferencing

Immersive audio-visual (re-)generation



Critical to achieve audio-visual *coherence*

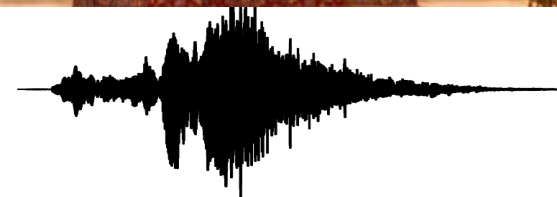
- Easier to understand
- Enhanced realism
- Smooth user experience

Two key visual associations

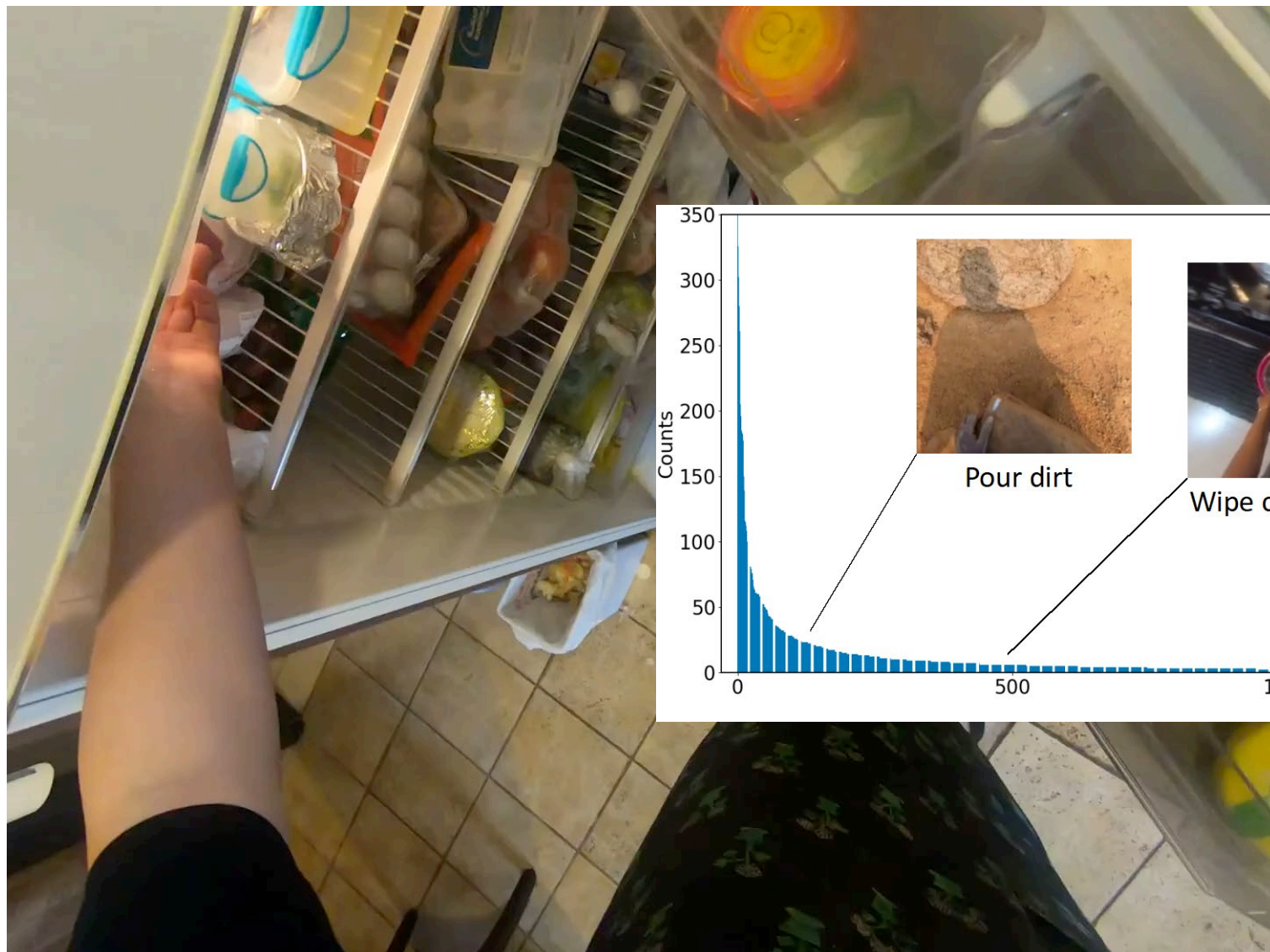
Actions



Scenes



Discovering sounding actions from in-the-wild video



Wide variety of **object interactions** → long tail of sounds

Discovering sounding actions

Goal: determine when sounds are directly caused by human action

Challenge: non-action sounds can be correlated with the visual signal

Temporal segments from narrated video

Ego4D¹/EPIC-Kitchens² have timestamped narrations describing atomic actions



C cuts the grass with sickle tool



C separates coconut leave stalks



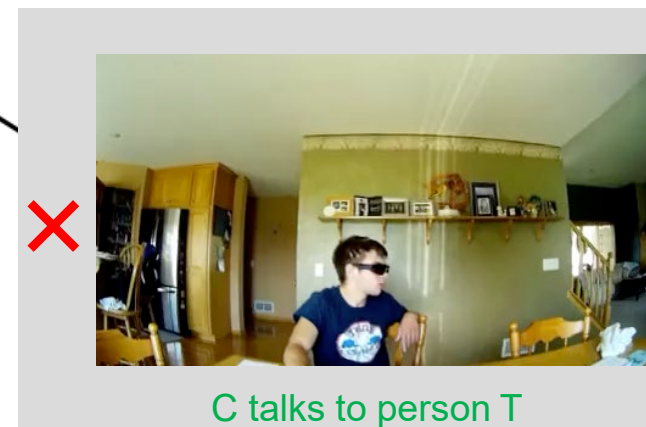
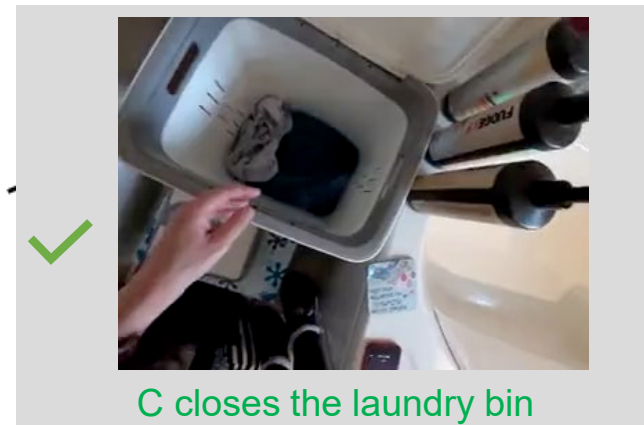
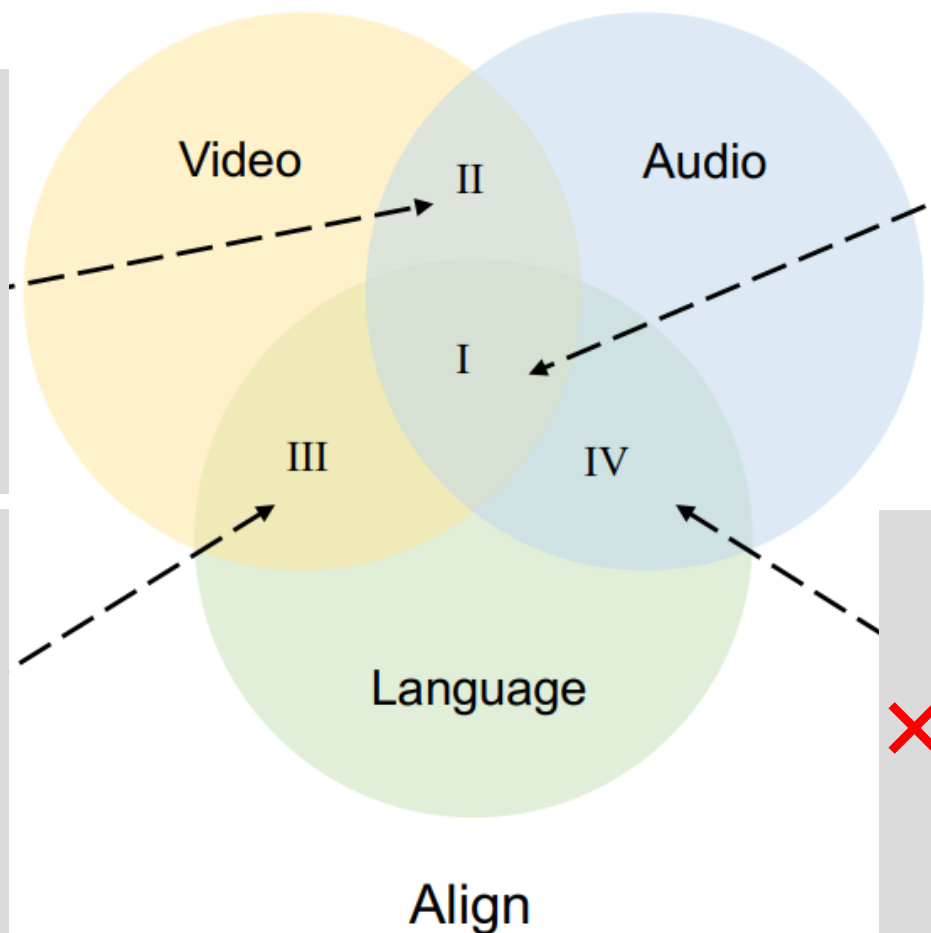
C moves a cutting machine with hands

¹Ego4D, Grauman et al., CVPR 2022

²EPIC-KITCHENS, Damen et al., ECCV 2018

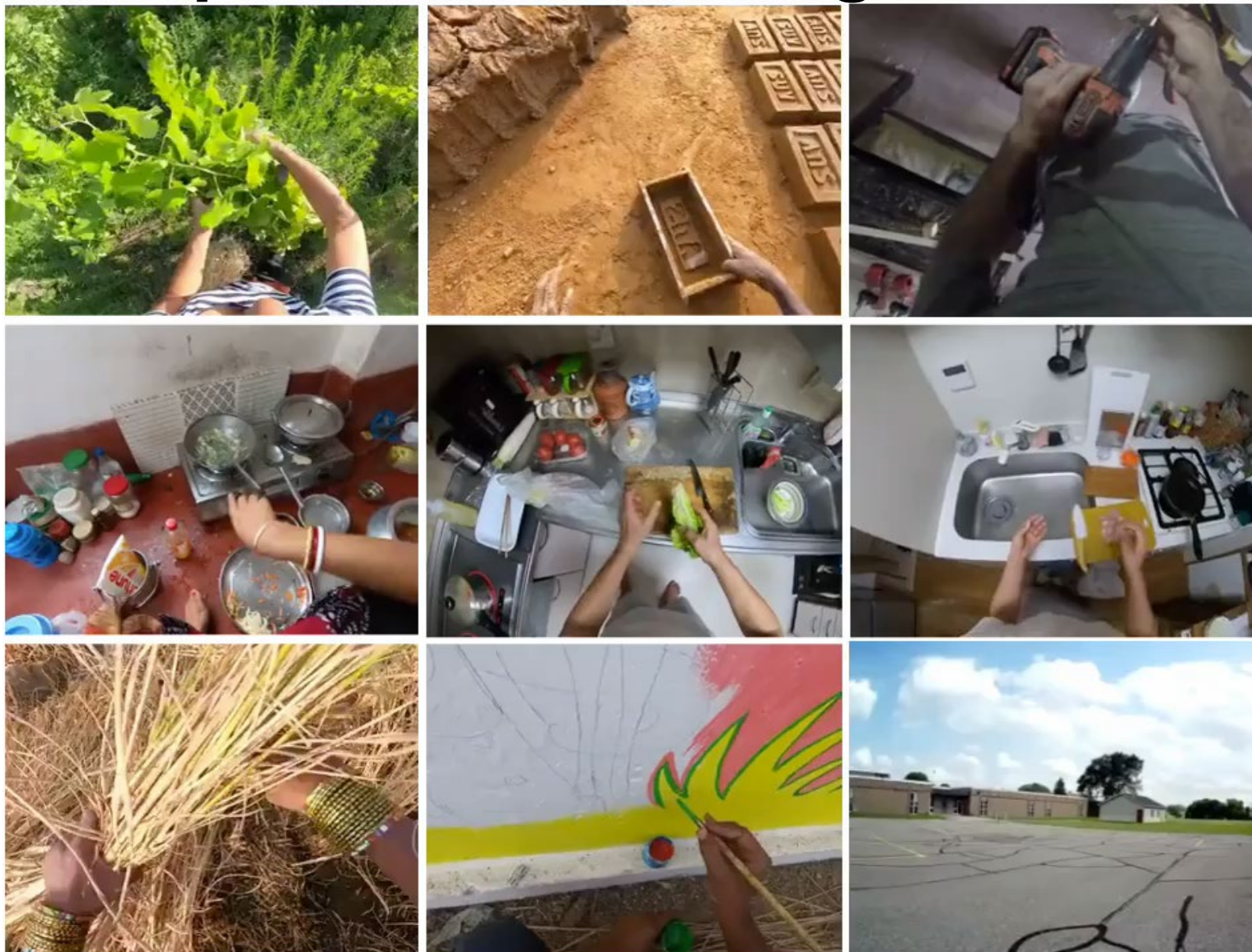
Discovering sounding actions from narrated video

Seek semantic agreement between video, audio and language

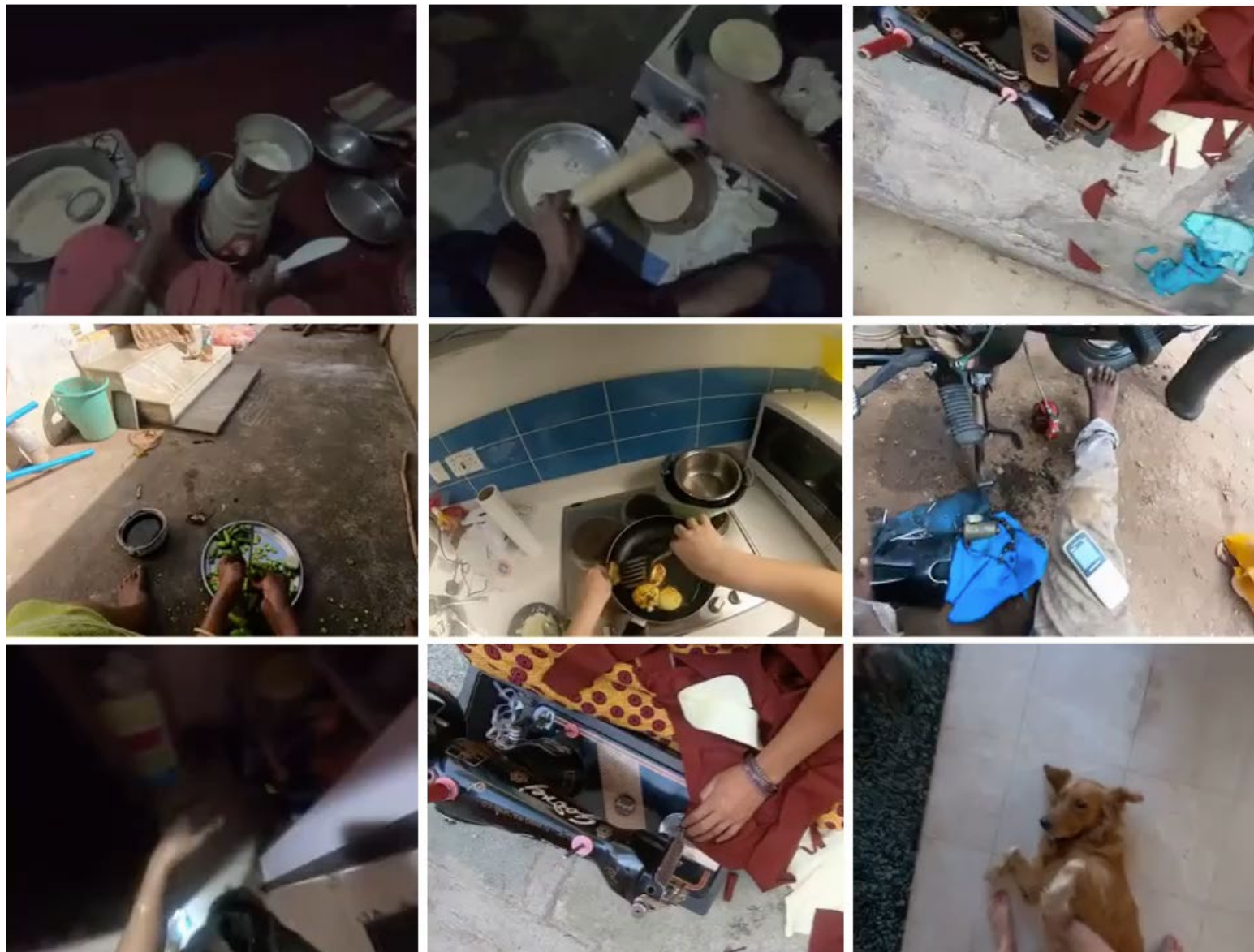


Novel “multimodal contrastive consensus” loss

Top-ranked sounding actions



Bottom-ranked sounding actions



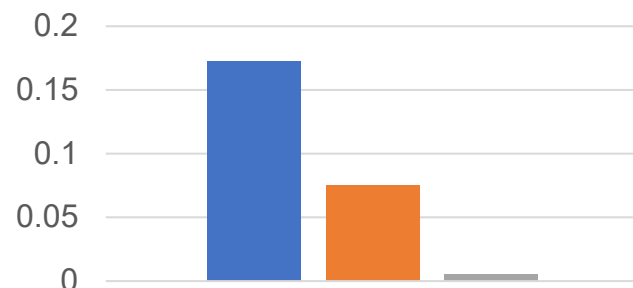
Is this a sounding action?



(Reference only) C drops the coconut on the tray



No sounding action



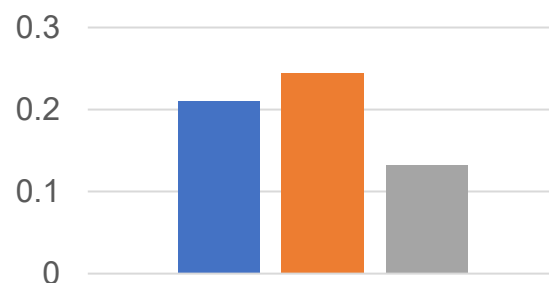
■ CMC ■ ImageBind ■ MC3 (Ours)



(Reference only) C lifts the left hand



No sounding action



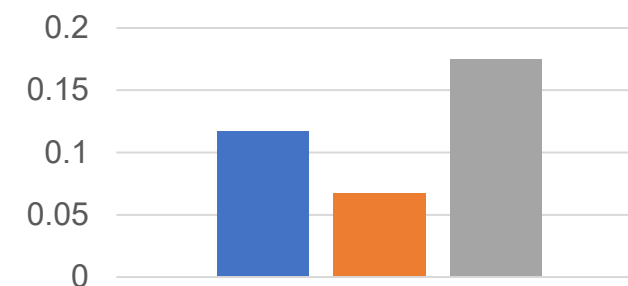
■ CMC ■ ImageBind ■ MC3 (Ours)



(Reference only) C rinses her hand with water



Sounding action



■ CMC ■ ImageBind ■ MC3 (Ours)

¹CMC, Tian et al., ECCV 2020

²ImageBind: Girdhar et al., CVPR 2023

Sounding action discovery accuracy

Results on Ego4D

				<i>AV</i>		<i>AL</i>	
				ROC	PR	ROC	PR
Random	✗	✗	✗	0.500	0.559	0.500	0.559
CLAP [1]	✓	✗	✓	-	-	0.637	0.695
CM-ACC [2]	✓	✓	✗	0.540	0.590	-	-
CMC [3]	✓	✓	✓	0.550	0.601	0.635	0.693
ImageBind [4]	✓	✓	✓	0.554	0.605	0.642	0.685
w/o $\mathcal{L}_{\text{consensus}}$	✓	✓	✓	0.563	0.615	0.635	0.694
w/o $\mathcal{L}_{\text{contrastive}}$	✓	✓	✓	0.436	0.493	0.584	0.620
w/o align-stage	✓	✓	✓	0.448	0.507	0.464	0.521
MC3	✓	✓	✓	0.598	0.666	0.658	0.715

bi-modal

bi-modal

trimodal joint

trimodal sequential

¹CLAP, Wu et al., ICASSP 2023

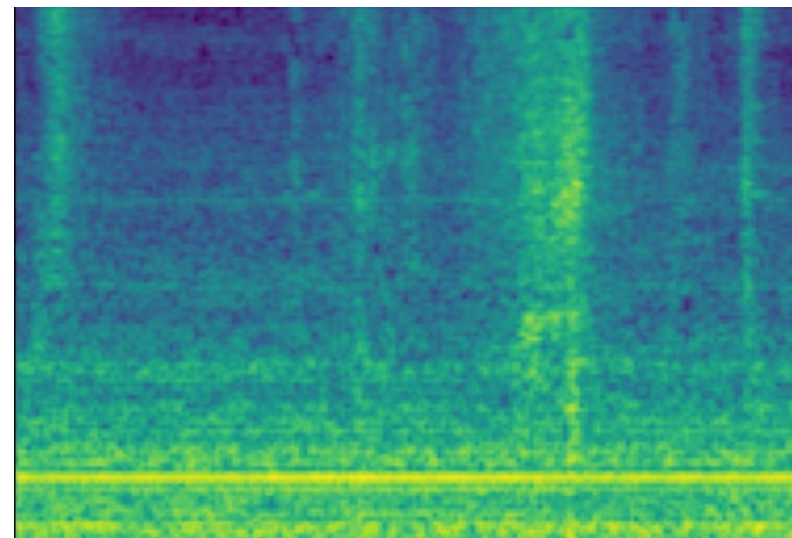
²CM-ACC: Ma et al., ICLR 2021

³CMC, Tian et al., ECCV 2020

⁴ImageBind: Girdhar et al., CVPR 2023

- Outperforming existing bi-modal or trimodal losses
- Both contrastive and consensus losses are important for learning

How to *generate* action sounds?



Given a silent video, can we generate plausible action sounds?

Challenge

In-the-wild videos have coupled ambient/background and action sounds



Offscreen machine sound



Birds chirping in the background

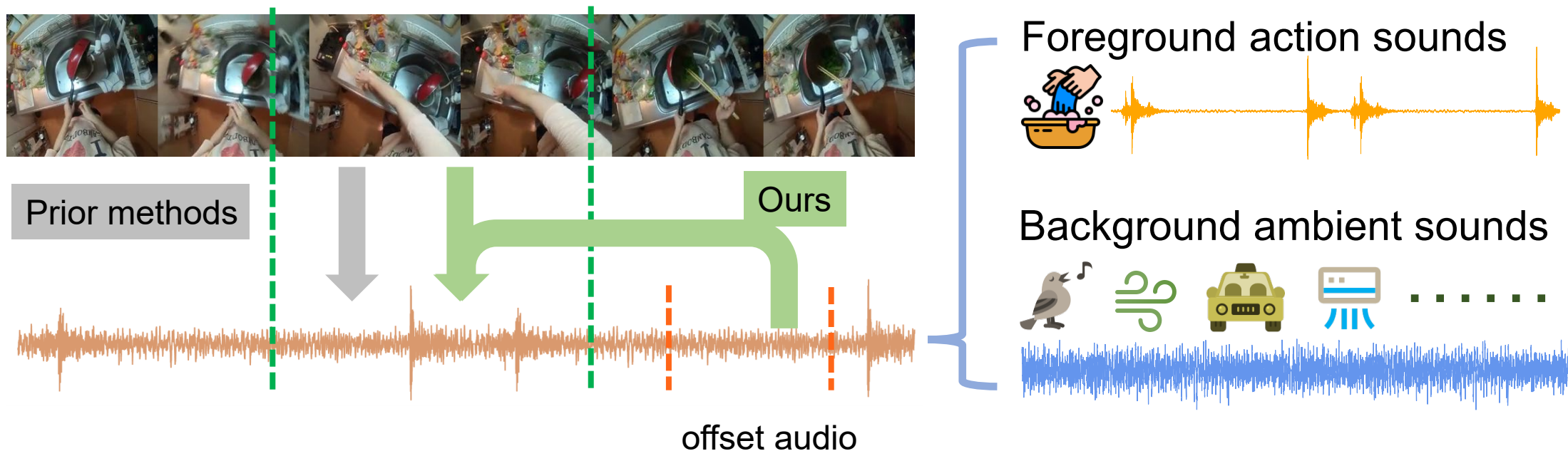


Low frequency buzzing sound

High risk of hallucination if we ignore this overlap in training,
yet we have no ground truth for ambient/action separated sounds.

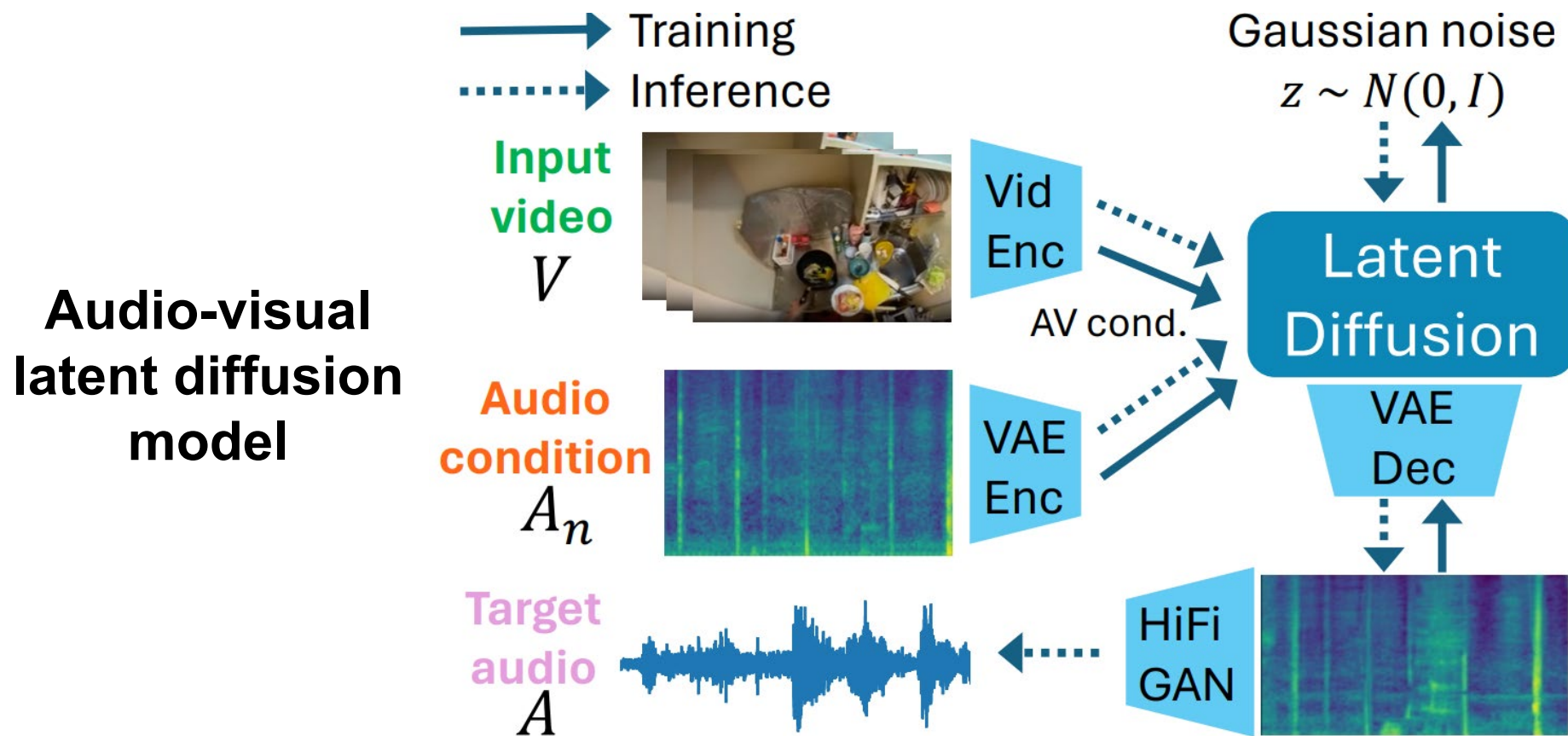
Action2sound: ambient-aware sound generation

Insight: Ambient sound tends to stay similar throughout a long video



Train: Conditioning on temporally nearby audio encourages the model to focus on action sound generation, while learning to ignore the ambient sound.

Action2sound: ambient-aware sound generation



Train: Conditioning on temporally nearby audio encourages the model to focus on action sound generation, while learning to ignore the ambient sound.

HiFi-GAN, Kong et al. 2020

Chen and Peng et al., Action2Sound: Ambient-Aware Generation of Action Sounds from Egocentric Videos, ECCV 2024

Action2sound: ambient-aware sound generation

Ours action-ambient



Diff-Foley

Ours action-focused



Original video



¹Diff-Foley, Luo et al.,
NeurIPS 2023

Action2sound: ambient-aware sound generation

Ours action-ambient



Ours action-focused



Diff-Foley



Original video



¹Diff-Foley, Luo et al.,
NeurIPS 2023

Action2sound: ambient-aware sound generation

Train on real video → test on games



Game clip



Ours (generated from
visual frames alone)

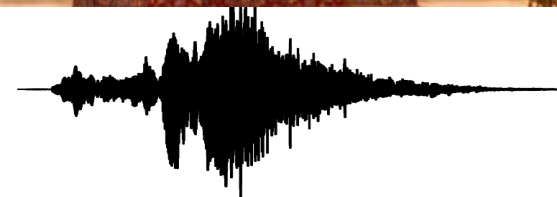
Video source: Clash Of Chefs

Two key visual associations

Actions



Scenes



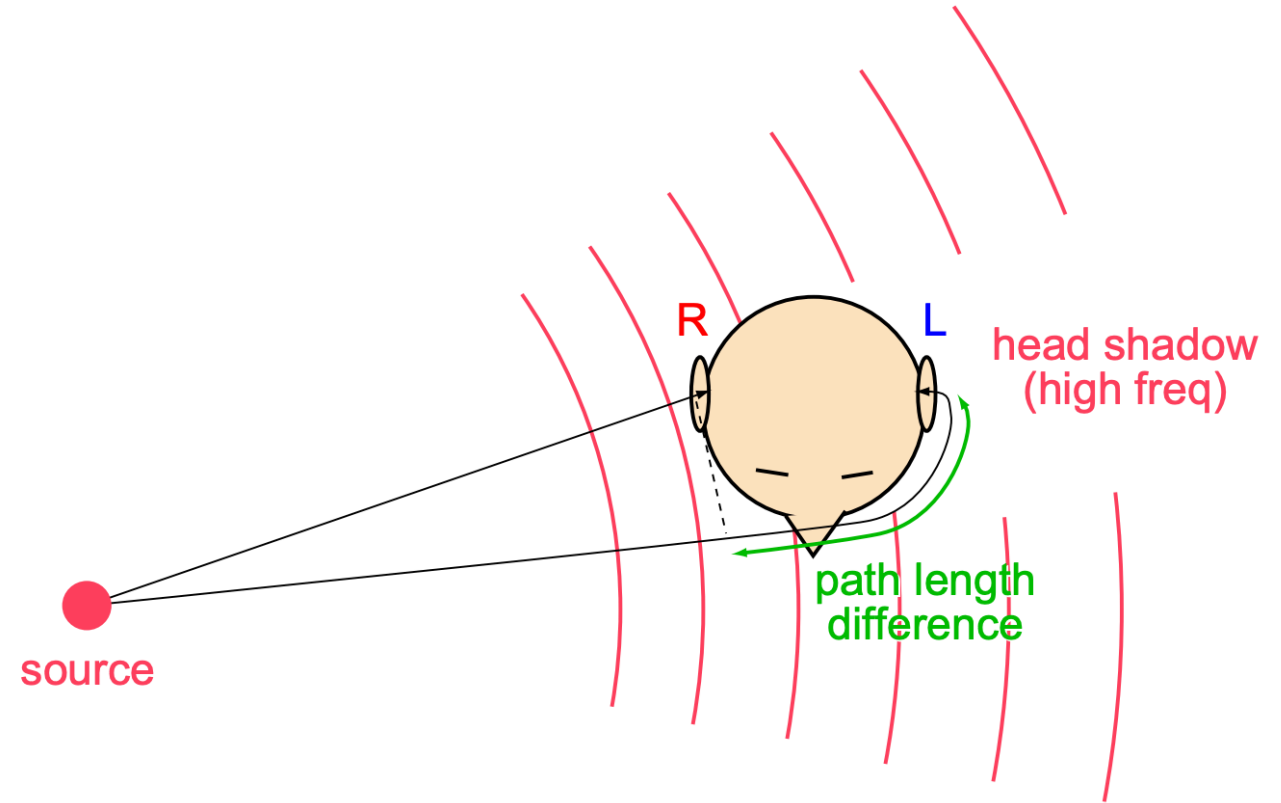
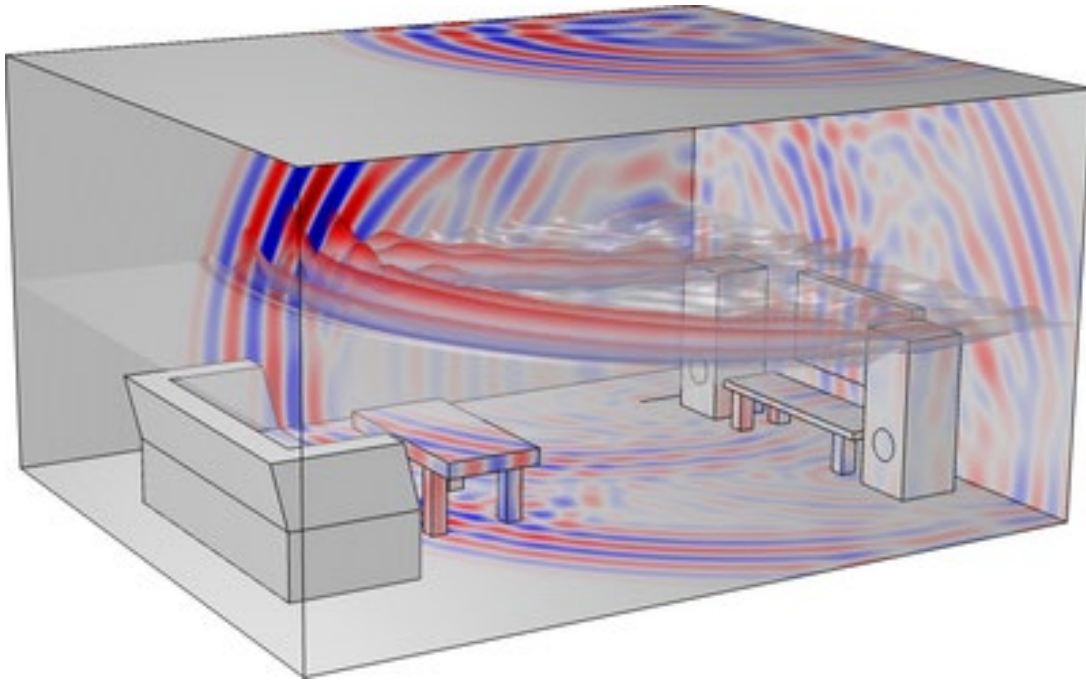
1 drum kit, 5 different spaces



Source: Shred Shed Studio

Kristen Grauman, UT Austin

Spatial effects in audio



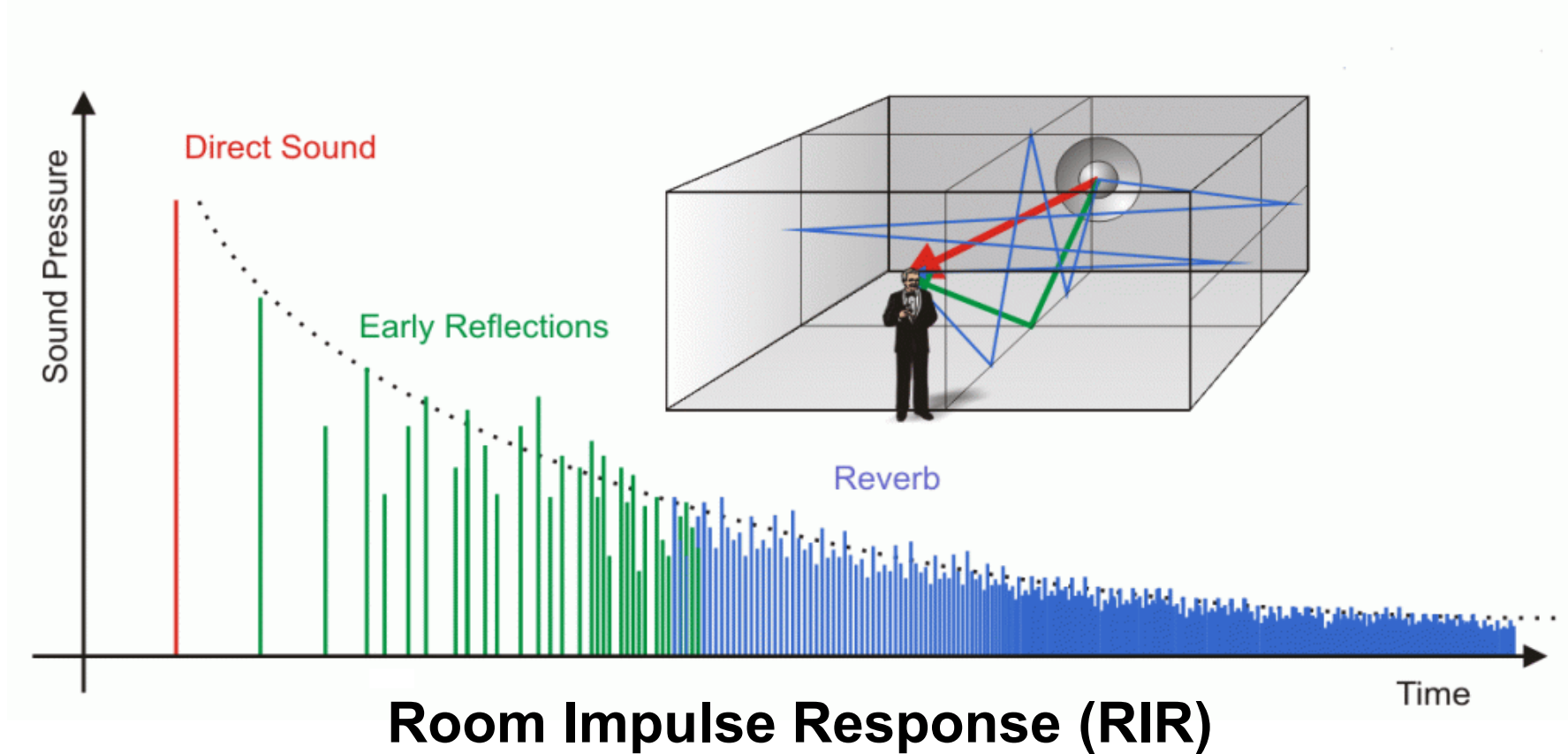
Factors from 3D environment:

- Geometry of the space
- Materials in the room
- Position of source and receiver

Agent's spatial hearing cues:

- Interaural time difference (ITD),
- Interaural level difference (ILD)
- Spectral detail (from pinna reflections)

Modelling scene acoustics via room impulse responses

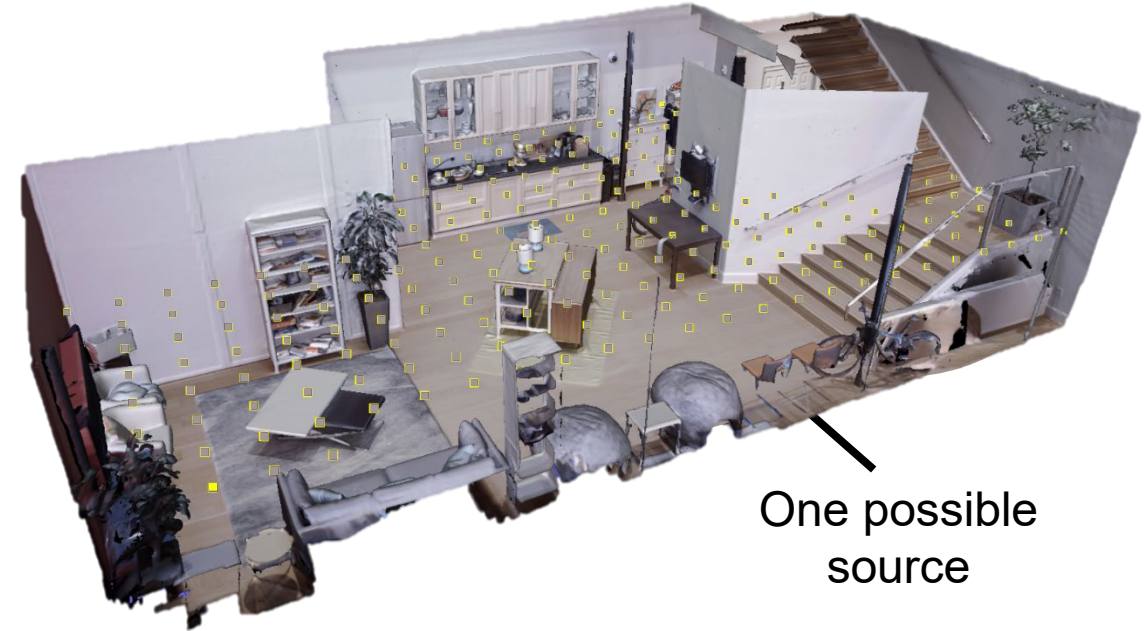


RIR is “ticket” to
acoustically
accurate audio
generation!

SoundSpaces audio simulation platform

<https://github.com/facebookresearch/sound-spaces>

- Visually realistic real-world 3D environments (Matterport3D, Replica, Gibson, HM3D, your choice...)
- Acoustically realistic (geometry, materials, source location) binaural sound in real-time, for waveform of your choice
- Room impulse response (RIR) for any source x receiver location, on-the-fly
- Habitat-compatible

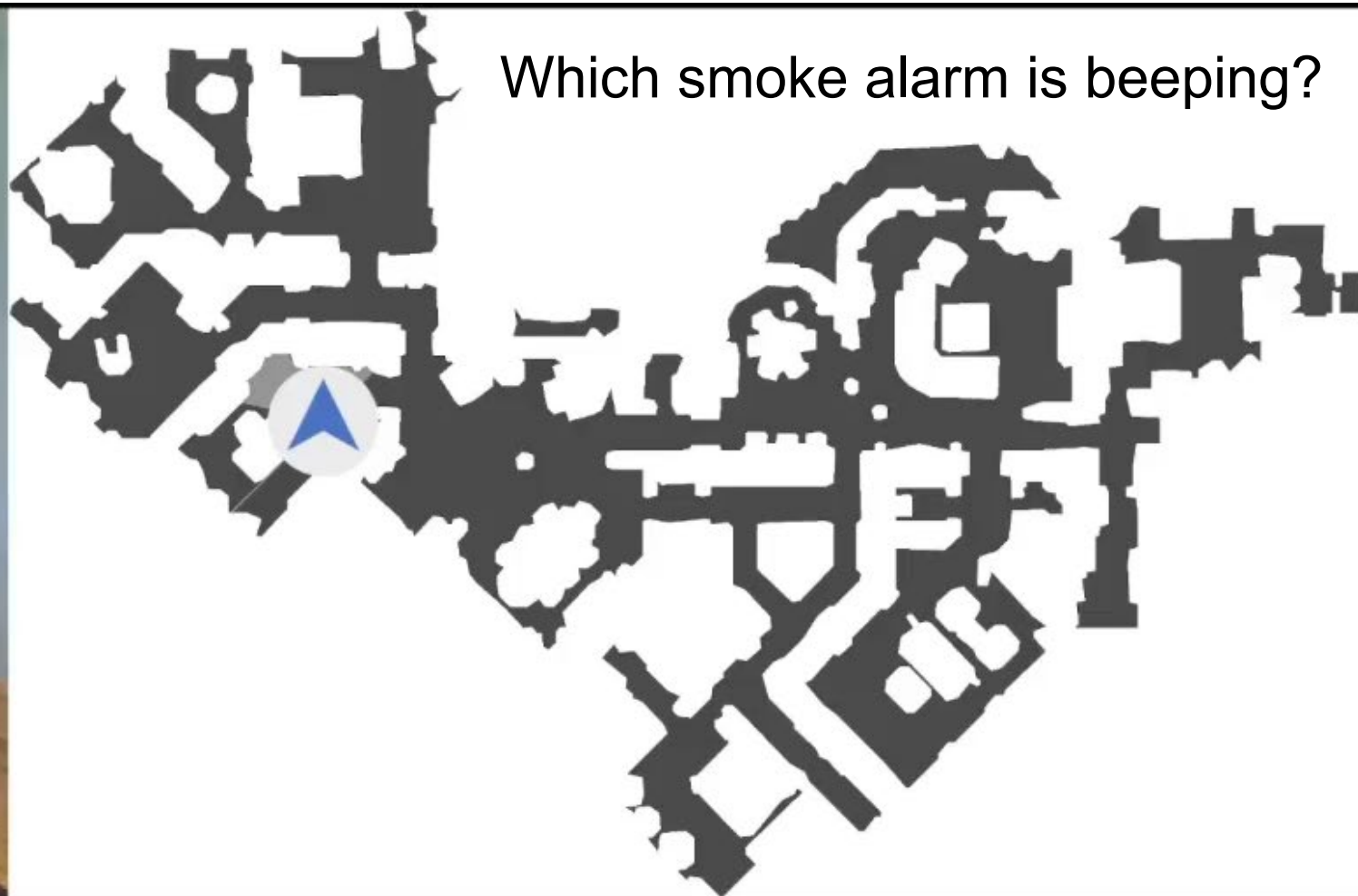


SoundSpaces audio simulation

C. Chen*, U. Jain*, et al., SoundSpaces, ECCV 2020 & SoundSpaces 2.0, NeurIPS 2022



Agent view



Which smoke alarm is beeping?

Top-down map (unknown to the agent)

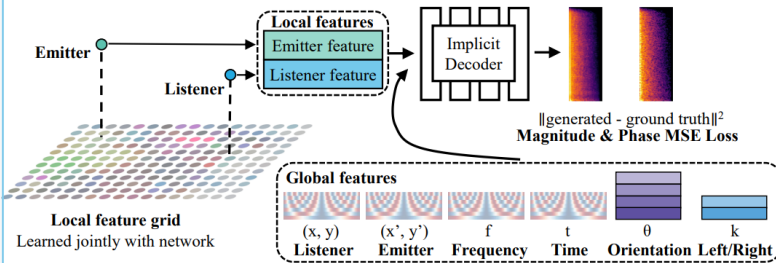
Listen with headphones online for spatial sound experience http://vision.cs.utexas.edu/projects/audio_visual_navigation/

How to build an acoustic
model for a new environment?

Prior work: building a scene acoustics model

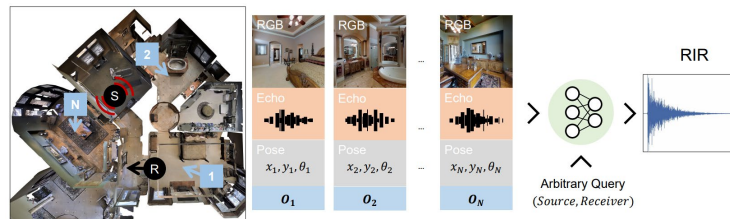
Neural Acoustic Fields (NAF)¹

Densely samples space to build Neural Field acoustic representation



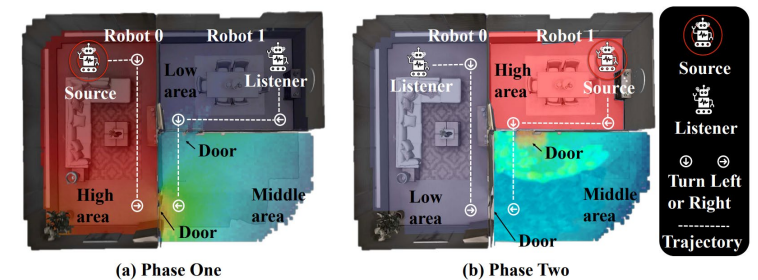
Few-ShotRIR²

Builds acoustic context from fixed number of randomly selected samples



Measuring Acoustics with Collaborative Multiple Agents³

Two agents navigate a space and build acoustic map using local reward



Require knowledge of room geometry – **often unrealistic** ✗

Dense sampling in the space – **expensive and time-consuming** ✗

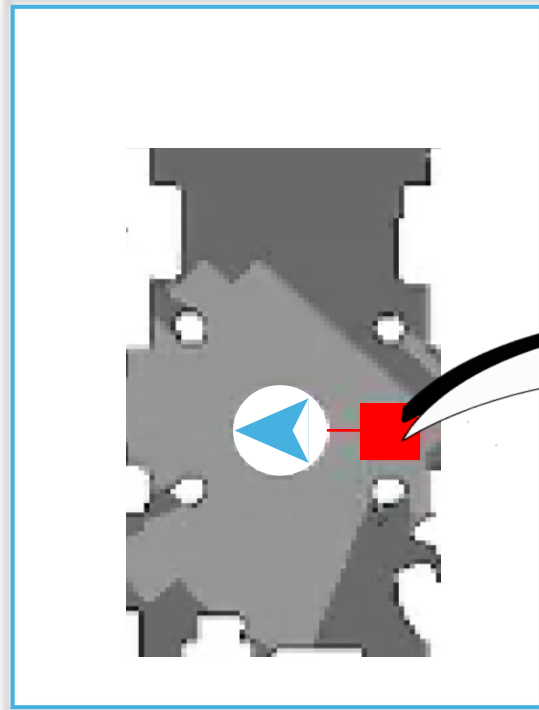
[1] A. Luo, Y. Du, M. J. Tarr, J. B. Tenenbaum, A. Torralba, and C. Gan, "Learning Neural Acoustic Fields," NeurIPS 2022

[2] S. Majumder, C. Chen, Z. Al-Halah, and K. Grauman, "Few-Shot Audio-Visual Learning of Environment Acoustics," NeurIPS, 2022

[3] Y. Yu, C. Chen, L. Cao, F. Yang, and F. Sun, "Measuring Acoustics with Collaborative Multiple Agents," IJCAI, 2023

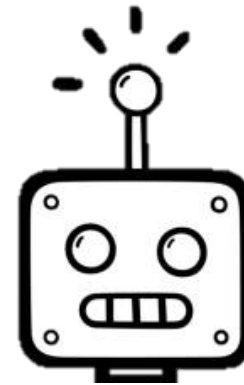
“Sampling” an audio-visual observation

Environment Floorplan

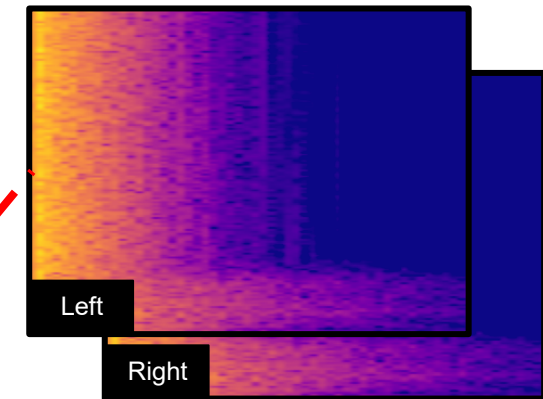


■ = sampling location

◀ = agent



Echo Response  

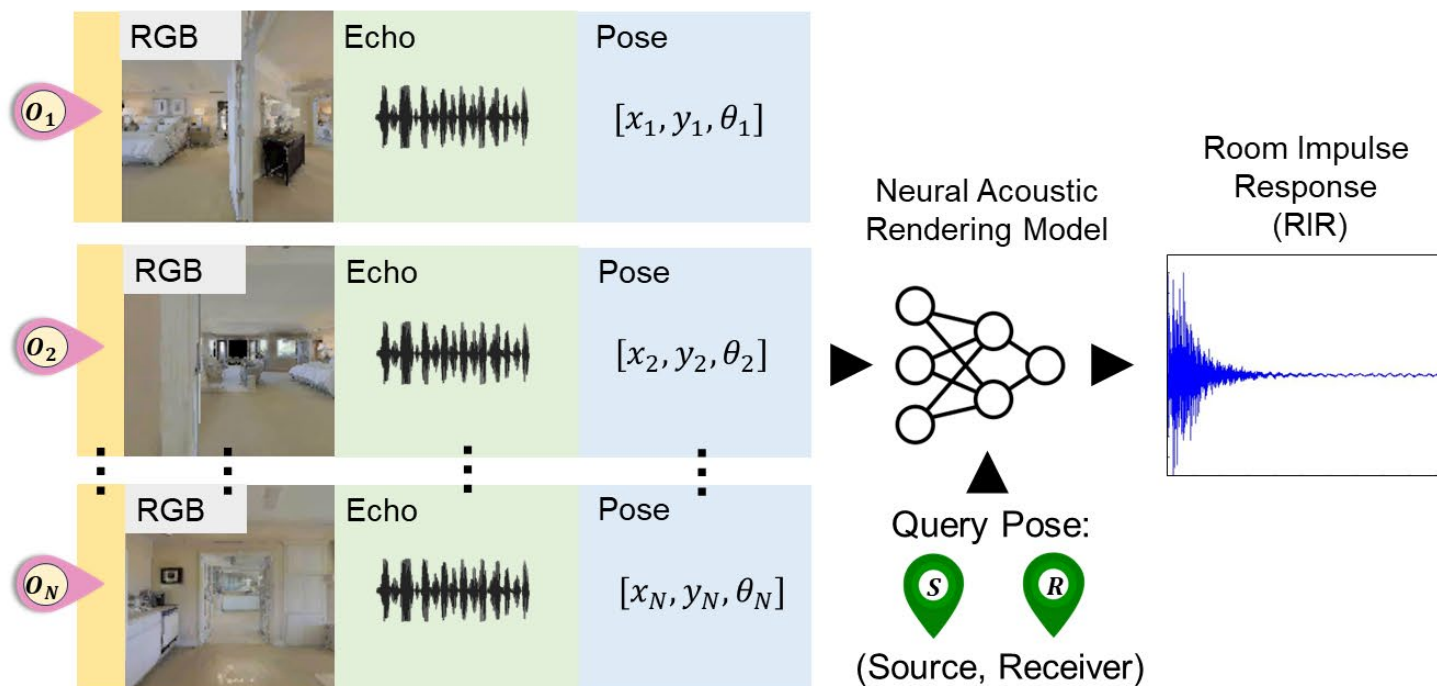
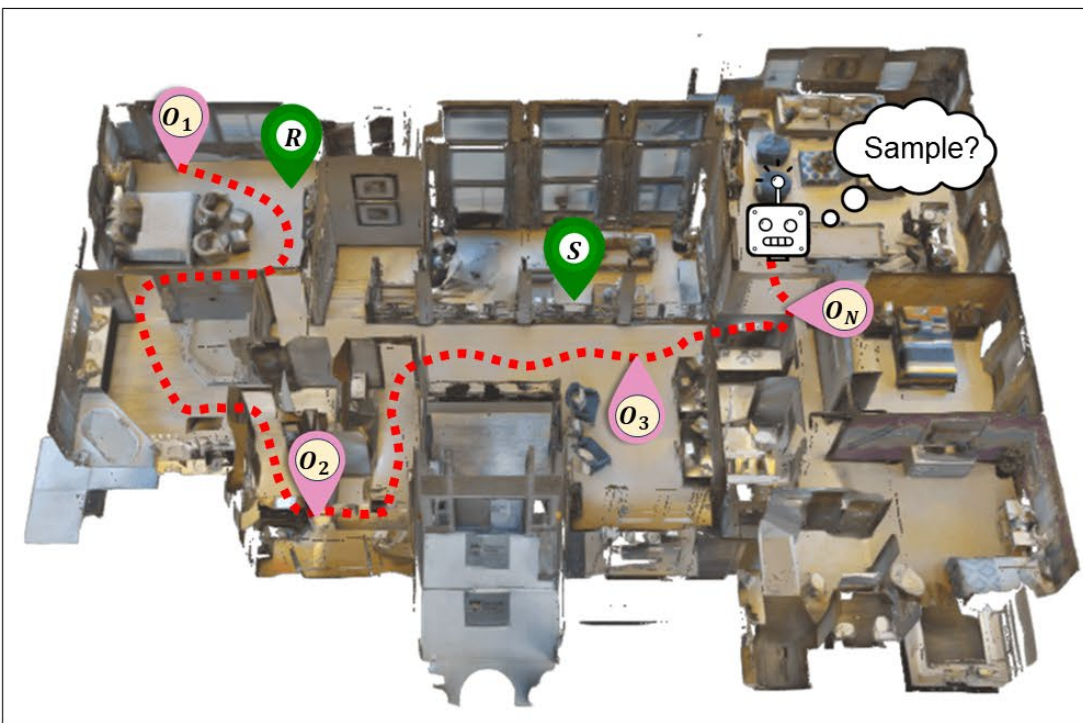


RGB-D 



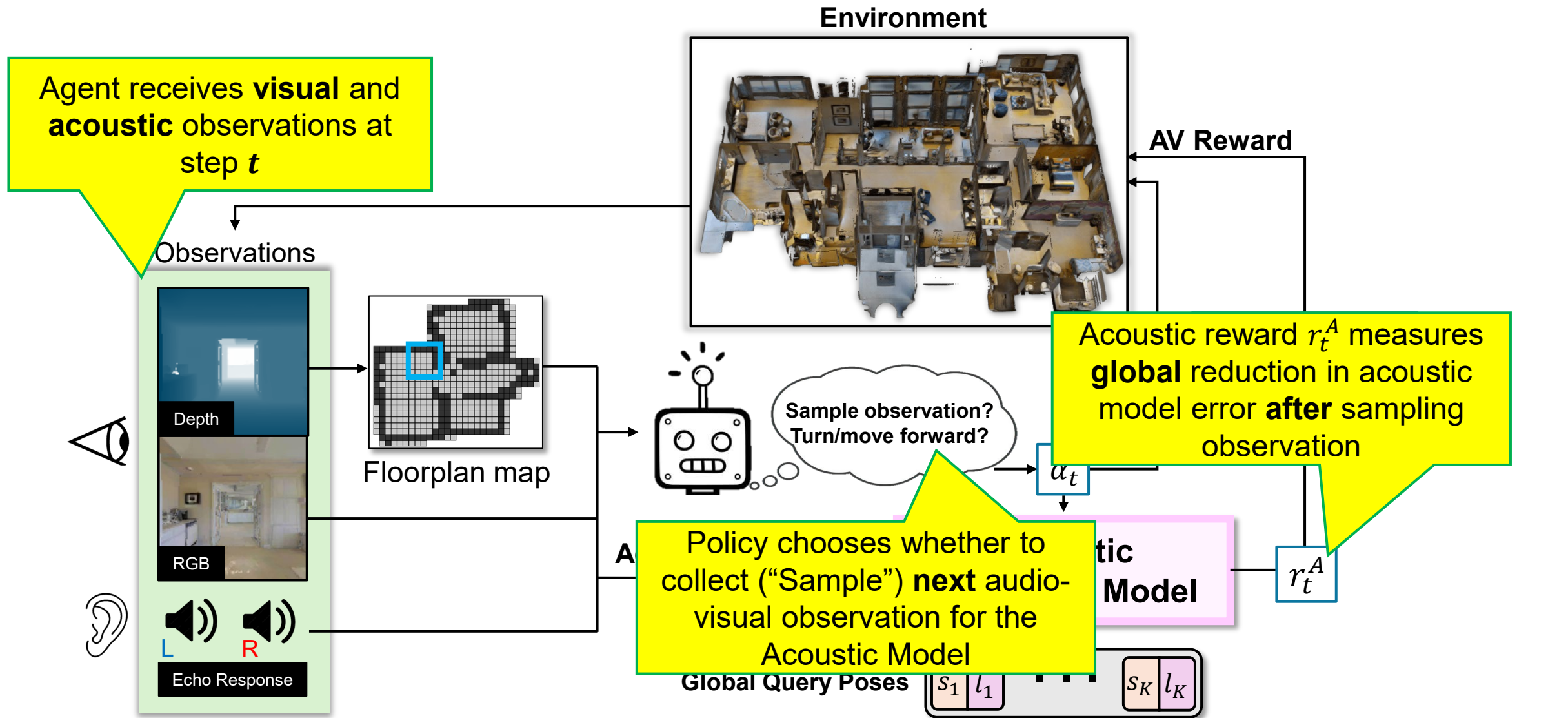
Goal: Active acoustic sampling

Agent must **actively select** audio-visual observations $\{o_i\}$ as it navigates an **unmapped** scene, constructing an acoustic model of the environment.

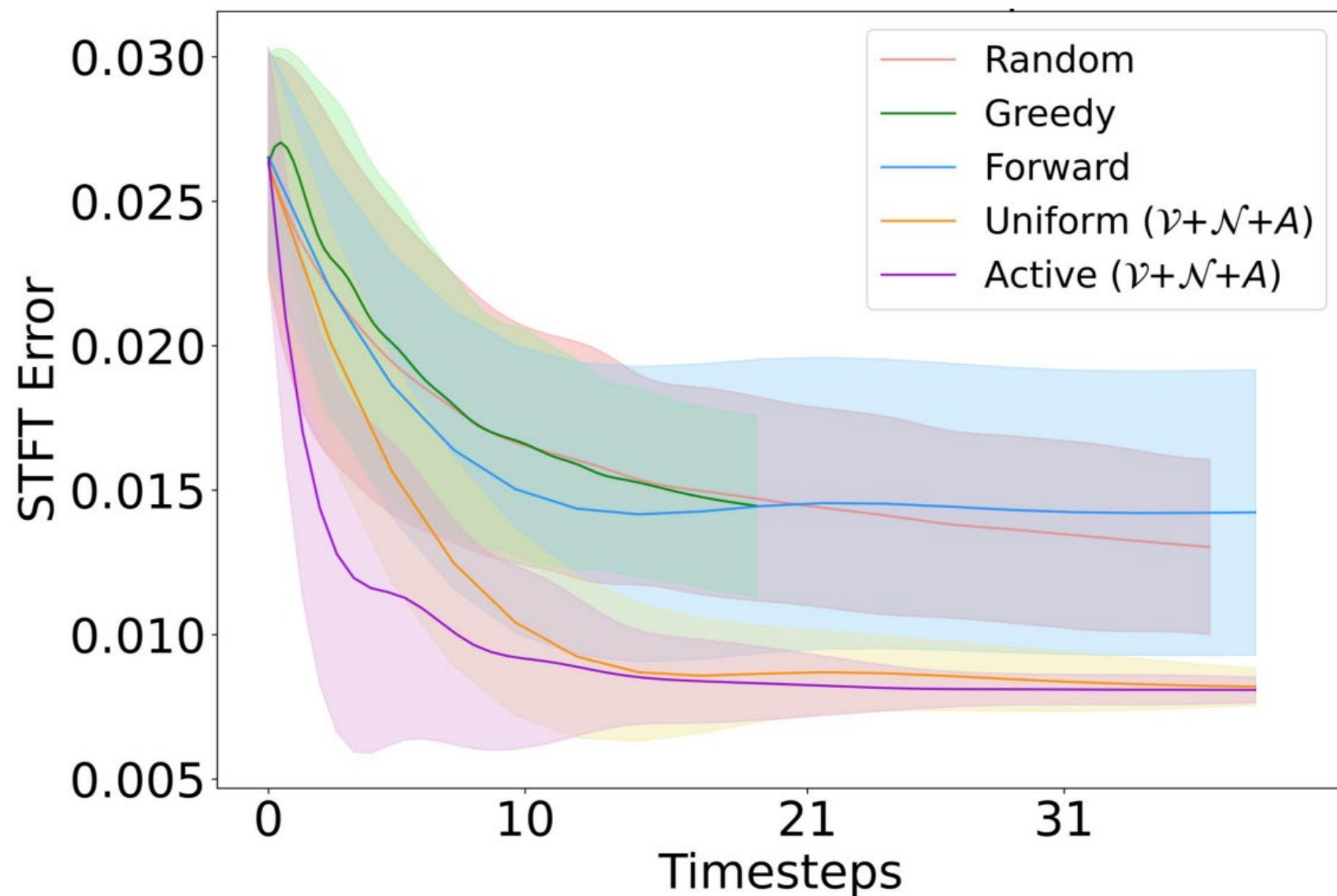


Agent has **no prior knowledge of the scene's floorplan or geometry**, and must complete exploration within a budget of T timesteps and N samples

ActiveRIR: an RL approach



ActiveRIR results



ActiveRIR (purple)
rapidly minimizes
acoustic model error
using fewer steps

ActiveRIR acoustic exploration

Passive sampling agent



Agent “wastes” context on **spatially redundant observations** ✗

Agent explores only a **small region of scene** ✗

Two key visual associations

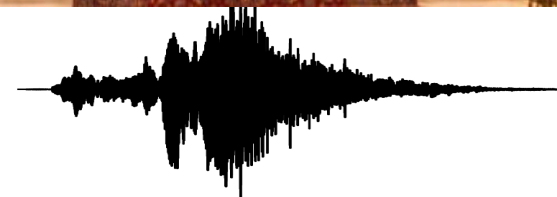
Actions



Scenes

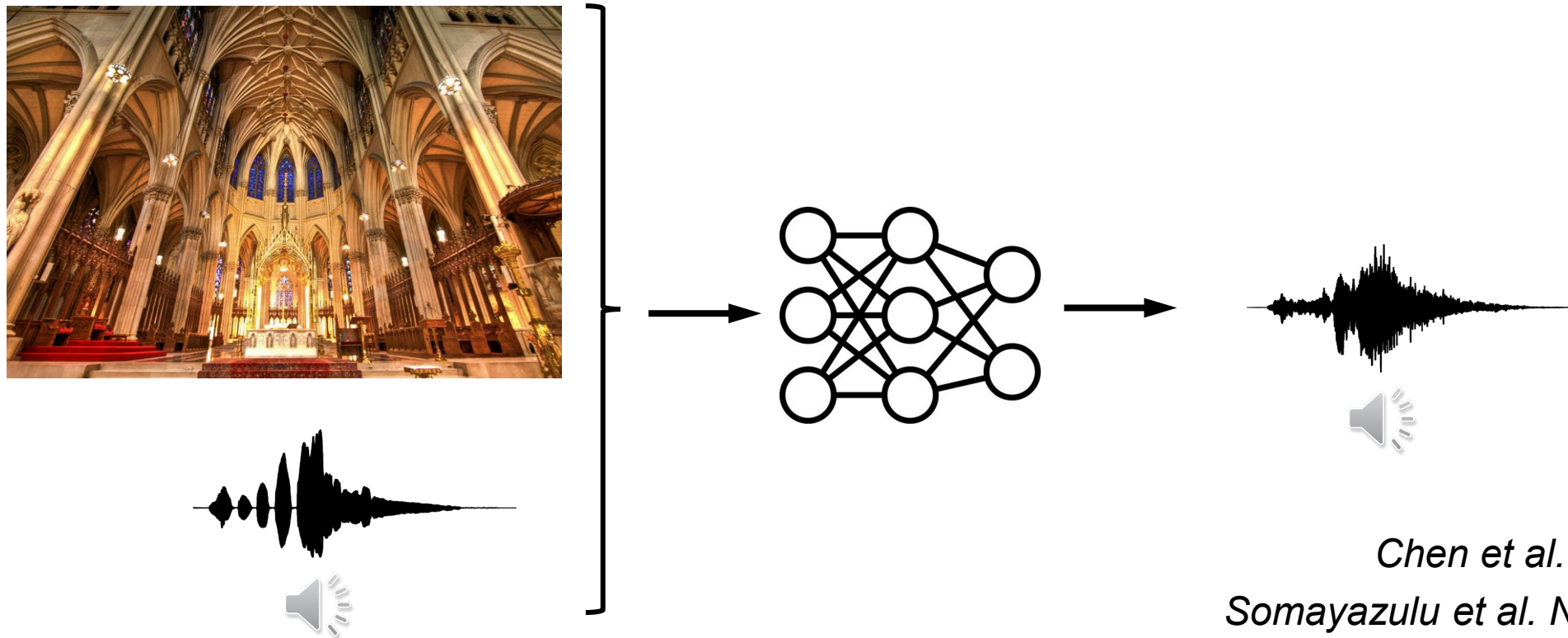


What if we have no physical access to the environment?



Our idea: Visual acoustic matching

Goal: Transform the sound recorded in one space to sound like it was instead recorded in a target visual scene.

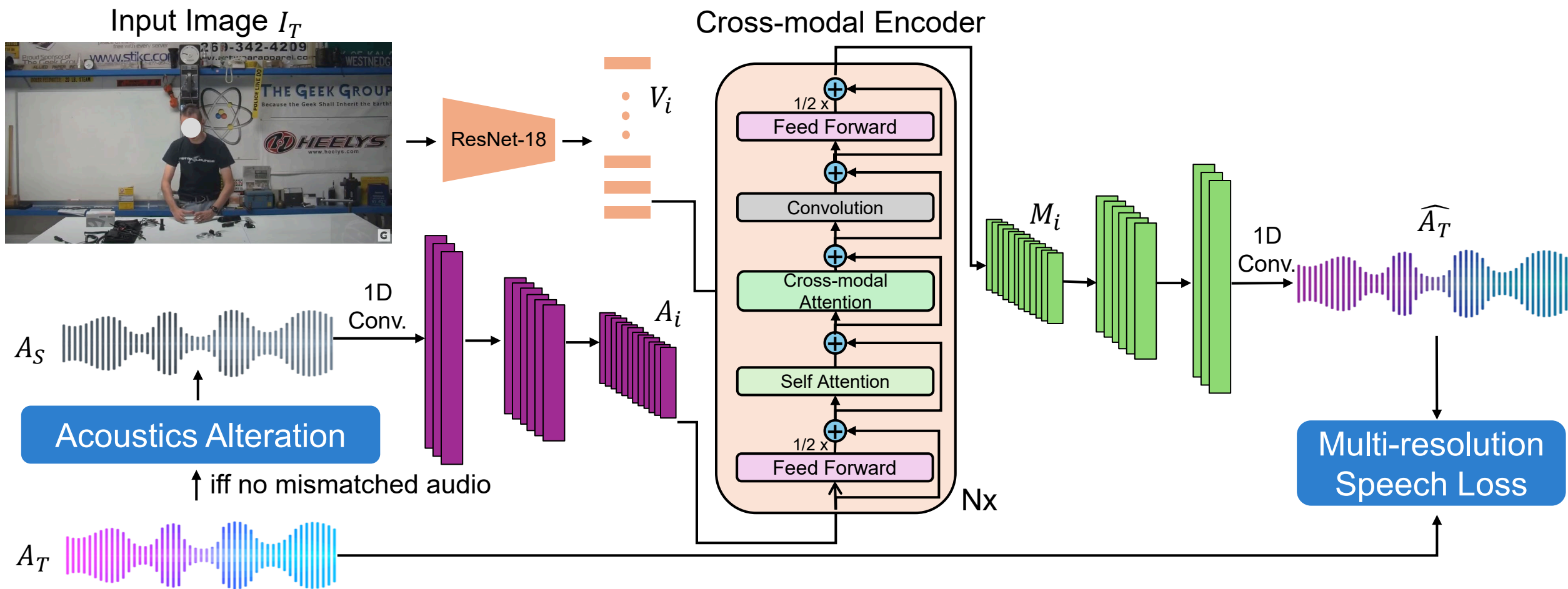


Chen et al. CVPR 2022

Somayazulu et al. NeurIPS 2023

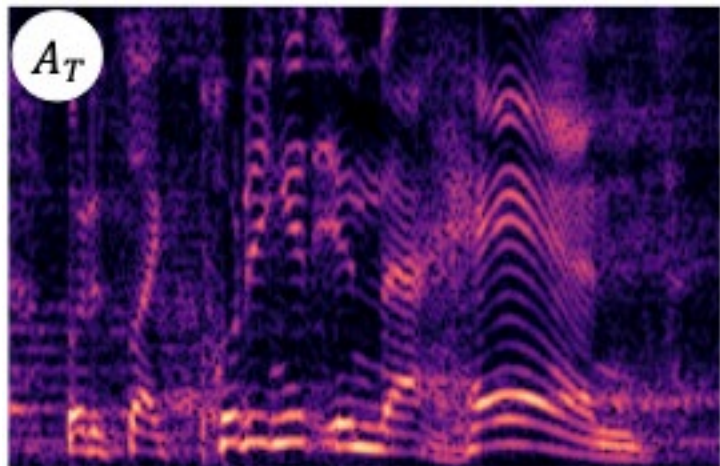
Prior work in acoustic matching – audio-based and typically require reference audio in target environment [Steinmetz et al. 2021; Valimaki et al. 2016; Su et al. 2020; Koo et al. 2021; Sarroff et al. 2020]

Audio-Visual Transformer for Audio Generation (AViTAR)



Acoustic alteration for self-supervised training

Audio in target
environment (GT)



“Source” audio
preserves content
but has mismatched
acoustics

Allows training directly on Web videos!

Chen et al. CVPR 2022
Somayazulu et al. NeurIPS 2023

Visual acoustic matching results

Office



Garage



Auditorium



Input



AViTAR



Reverb time

0.34s



0.40s



0.58s

AViTAR reasons about the image content and learns to inject more reverberation into the speech as the environment gets larger.

Visual acoustic matching results



Augmented/mixed reality



Video conference

Visual acoustic matching results

	<i>SoundSpaces-Speech</i>						<i>Acoustic AVSpeech</i>			
	<i>Seen</i>			<i>Unseen</i>			<i>Seen</i>		<i>Unseen</i>	
	STFT	RTE (s)	MOSE	STFT	RTE (s)	MOSE	RTE (s)	MOSE	RTE (s)	MOSE
Input audio	1.192	0.331	0.617	1.206	0.356	0.611	0.387	0.658	0.392	0.634
Blind Reverberator [61]	1.338	0.044	0.312	-	-	-	-	-	-	-
Image2Reverb [52]	2.538	0.293	0.508	2.318	0.317	0.518	-	-	-	-
AV U-Net [20]	0.638	0.095	0.353	0.658	0.118	0.367	0.156	0.570	0.188	0.540
AViTAR w/o visual	0.862	0.140	0.217	0.902	0.186	0.236	0.194	0.504	0.207	0.478
AViTAR	0.665	0.034	0.161	0.822	0.062	0.195	0.144	0.481	0.183	0.453

AV-Speech dataset: Ephrat et al. SIGGRAPH 2018

Blind Reverberator: Valimaki et al. More than 50 years of artificial reverberation, 2016

Image2Reverb: Singh et al. ICCV 2021

AV U-Net: Gao & Grauman CVPR 2019

+ User perception studies (not shown)

Summary

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Generating visually-coherent audio

- Discovering sounding actions from video via multimodal consensus (CVPR'24)
- Action2sound to disentangle ambient and action sounds (ECCV'24)
- ActiveRIR for embodied environment acoustics learning (IROS'24)
- Self-supervised visual acoustic matching (CVPR'22, NeurIPS'23)



Changan
Chen



Arjun
Somayazulu



Sagnik
Majumder



Ziad
Al-Halah